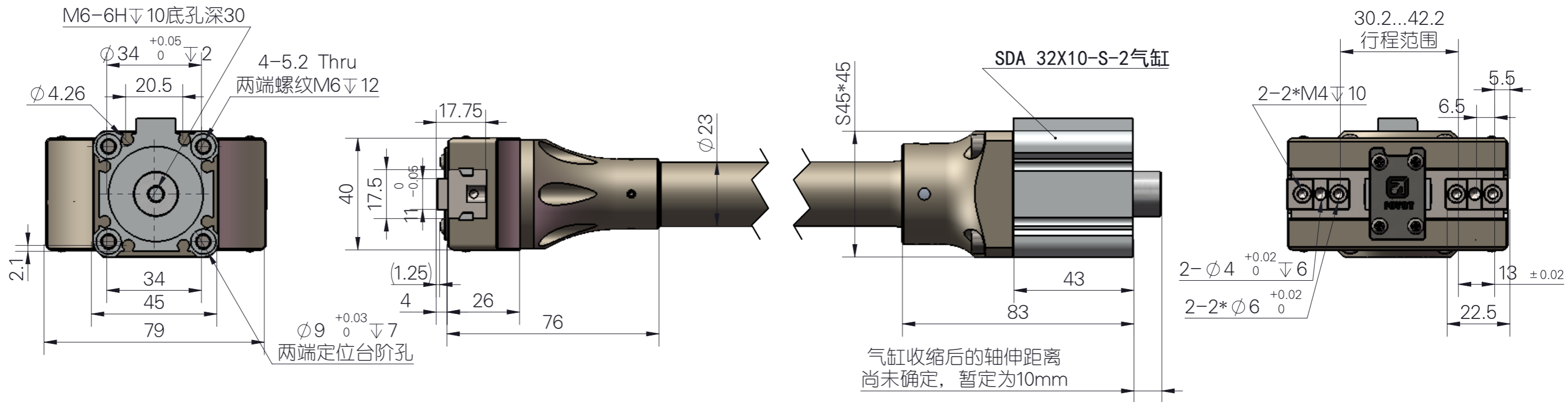
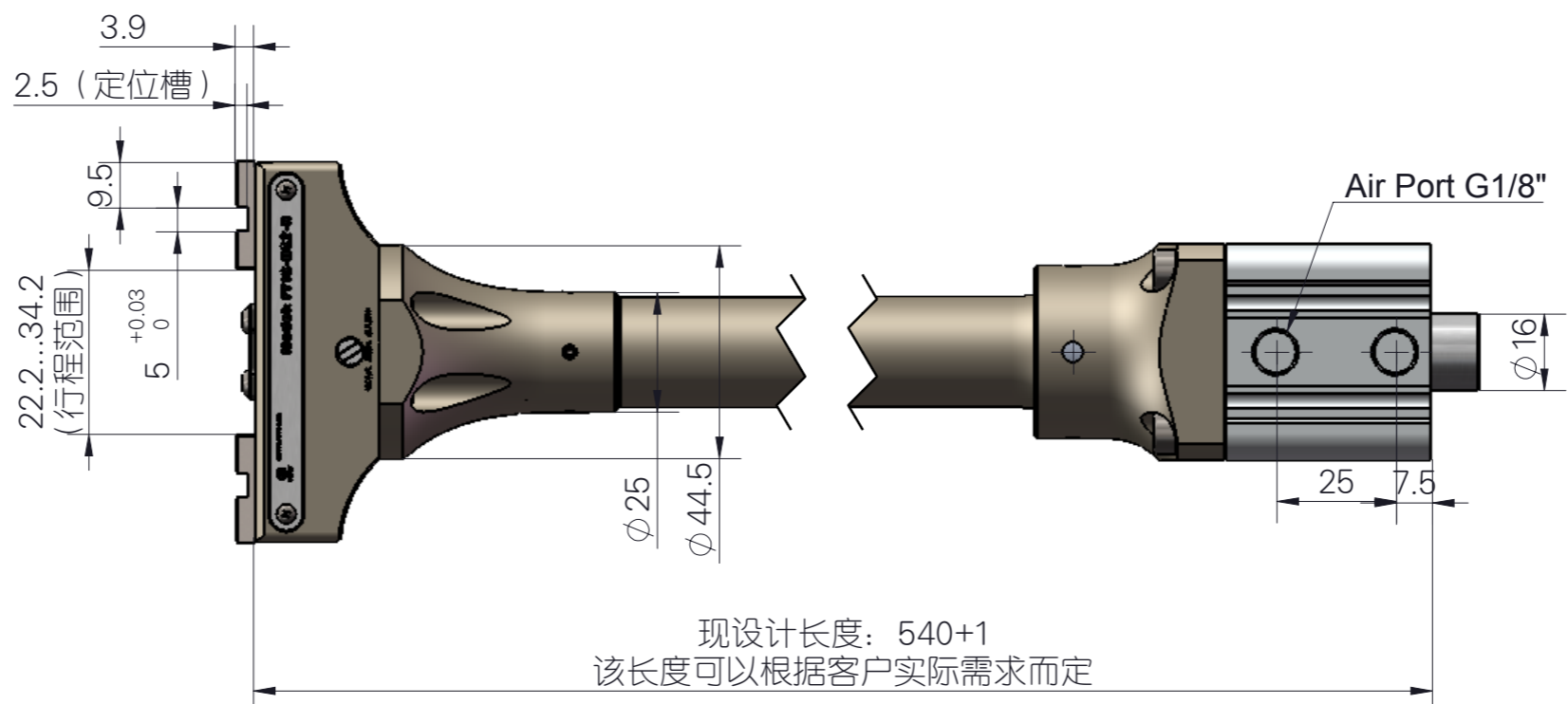


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 changed because of improvement thanks for your understanding



气缸收缩后的轴伸距离
 尚未确定, 暂定为10mm



现设计长度: 540+1
 该长度可以根据客户实际需求而定



警告:
 1.当操作夹爪工作时, 请人员务必远离夹爪和机器人的活动部位, 否则将会造成人身伤害的险;
 2.由于不同物件有其不同的摩擦系数, 当初次夹持工件时, 请在空旷场地进行试夹, 确保夹稳固后方可装机工作, 否则将会有跌落工件砸伤机器或人员的风险
 Warning:
 1.When operating the gripper, please keep away from it Gripper and robot's moving parts, otherwise it will Risk of personal injury;
 2. Because different objects have different friction coefficients, When clamping the workpiece for the first time, please try clamping in an open field. Ensure that the clamping is firm before the machine can work, otherwise it will There is a risk that falling workpieces may damage machines or personnel.

名称: 导轨款耐高温锻造平行夹爪-D32
 Name: Pneumatic parallel three claws
 型号 (Model): FY13-D32-HX540
 P:空气压力 (bar) P:Air Pressure(bar)
 L:到作用点距离 (mm) L:Exertion Length (mm)
 开闭范围 (Stoke): 12mm
 产品重量 (Weight): 4.05kg (长540mm时)
 最大附件长度 (Max. length attach): 60mm
 配管连接口 (Fitting size): G1/8 “
 理论夹持力-开 (Gripping force :Open): 459N
 理论夹持力-闭 (Gripping force : Close): 430N
 开闭时间 (Closeing/Opening time): 0.02/0.02sec
 重复精度 Repeat accuracy): 0.02mm
 连续使用次数 (Continuation usage amount): 60
 使用气压 (Operating pressure): 3-8bar
 润滑 (Lubrication): 不需要 (Needless)
 根据 IEC60529 标准安全防护: IP64
 所有数据在 7 Bar 时测量 (All data were measured at 6 Bar)
 重复精度: 连续动作 100 次以后的检测值
 After 100 consecutive strokes to end positions

推荐的工件重量 (Recommended workpiece weight): 2.1kg (max)