

本设计的结构和技术参数的知识产权归:
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本公司书面许可，不得复制、转让或仿制。
如经发现被复制或仿制将受到法律的严惩。

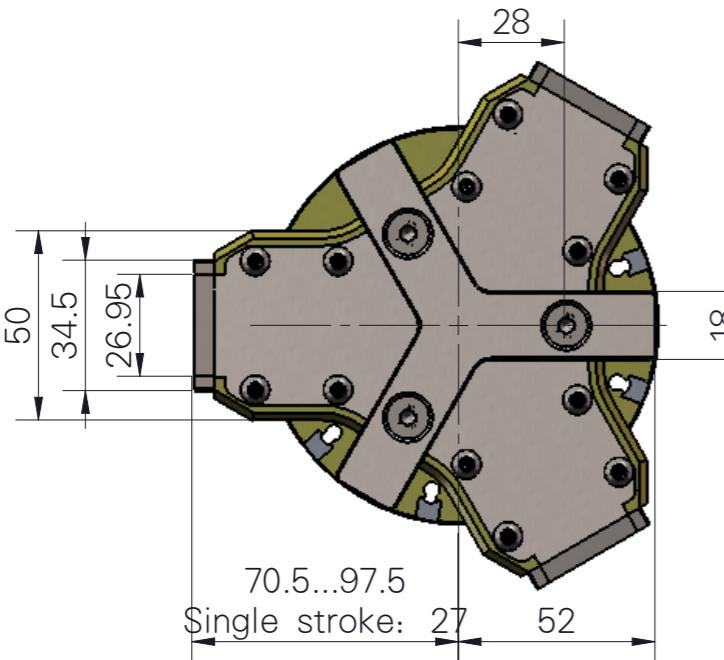
因改良等原因，规格以及外观有所变更时，不再另行通知，敬请谅解。
Without further notice if specification and exterior have been changed because of improvement thanks for your understanding.

警告

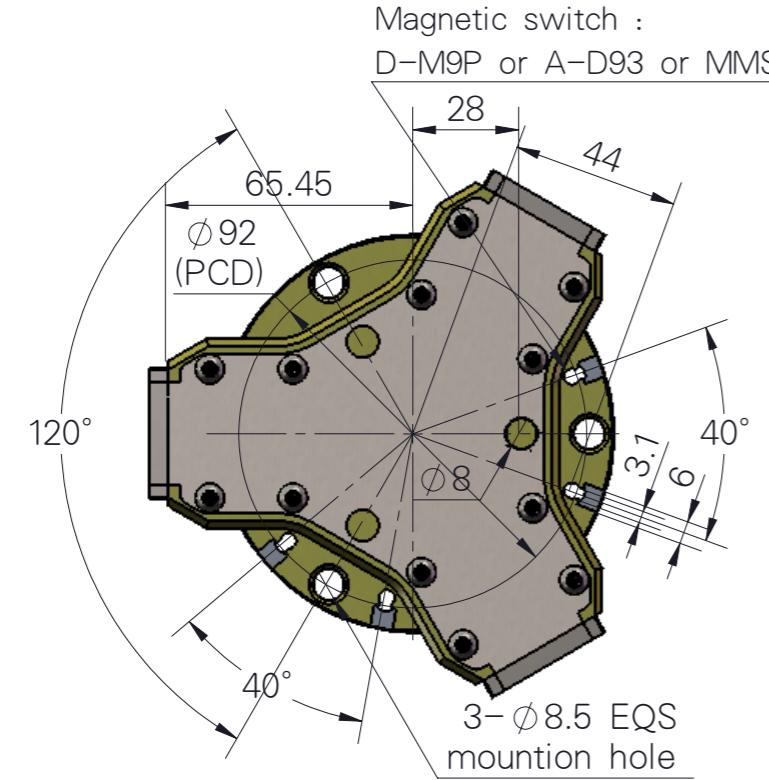
- 1.当操作夹爪工作时, 请人员务必远离夹爪和机器人的活动部位, 则将会造成人身伤害的险;
 - 2.由于不同物件有其不同的摩擦系数, 当初次夹持工件时, 请在场地进行试夹, 确保夹稳固后方可装机工作, 否则将会有跌落工件砸伤机器或人员的风险

Warning:

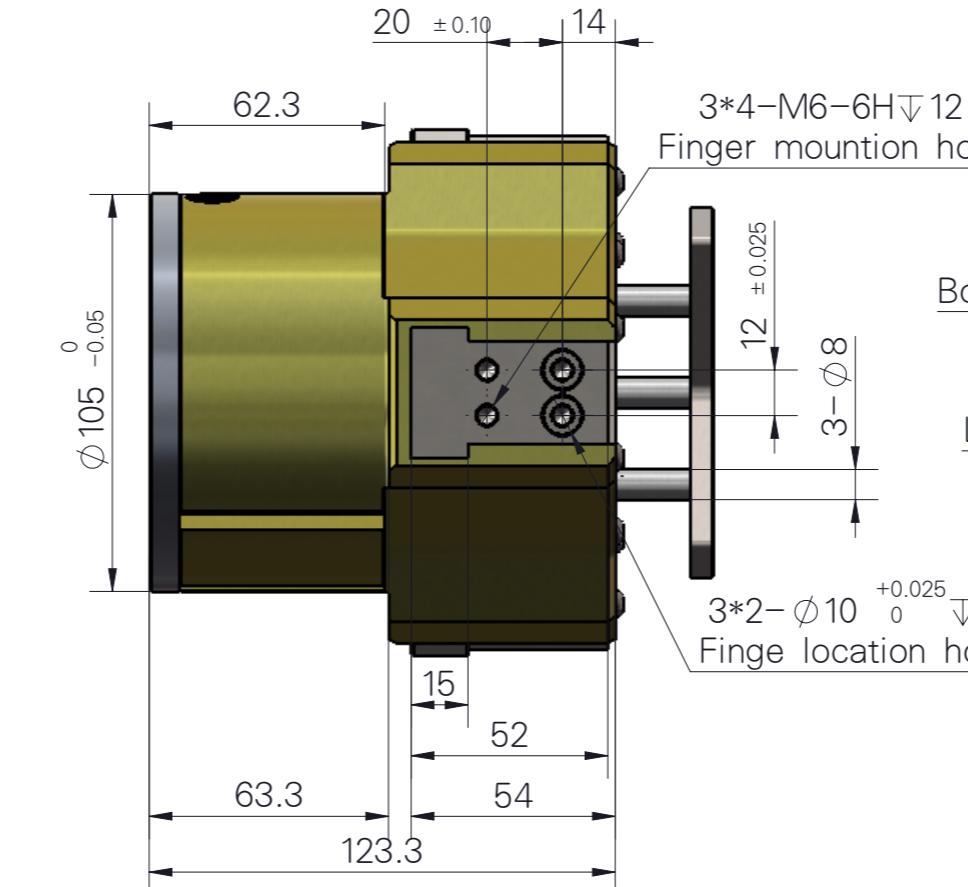
 1. When operating the gripper, please keep away from it Gripper and robot's moving parts, otherwise it will Risk of personal injury;
 2. Because different objects have different friction coefficients. When clamping the workpiece for the first time, please try clamping in an open field. Ensure that the clamping is firm before the machine can work, otherwise it will There is a risk that falling workpieces may damage machines or personnel.



PF(G1/
Air Po



Magnetic switch :
D-M9P or A-D93 or MMS



名称：气动平行两几

Name: Pneumatic parallel three claws

型号 (Model) : FY56N-D80-

开闭范围 (Stoke) : $2*27=54\text{mm}$

产品重量 (Weight):3.9K

最大附件长度(Max. length attach):130mm

配管连接口(Fitting size):PF(Φ)

理论夹持力-开(Gripping force :Open):3230N

理论夹持力-闭(Gripping force : Close):3028N

单循环空气消耗量(Air consumption per cycle): 163cm^3

开闭时间(Closing/Opening time): 0.8/0.8sec

重复精度Repeat accuracy):

连续使用次数(Continuation usage amount):60

使用气压(Operating pressure):3-8bar

周圍溫度(Ambient temperature): -

潤滑(Lubrication):不靈要 (Needless)

根据IEC60529标准安全防护·IP40

Safety protection according to IEC60529 standard:IP40

所有数据在6Bar时测量(All data were measured at 6Bar)

重复精度：连续动作100次以后的检测值

After 100 consecutive strokes to end positions