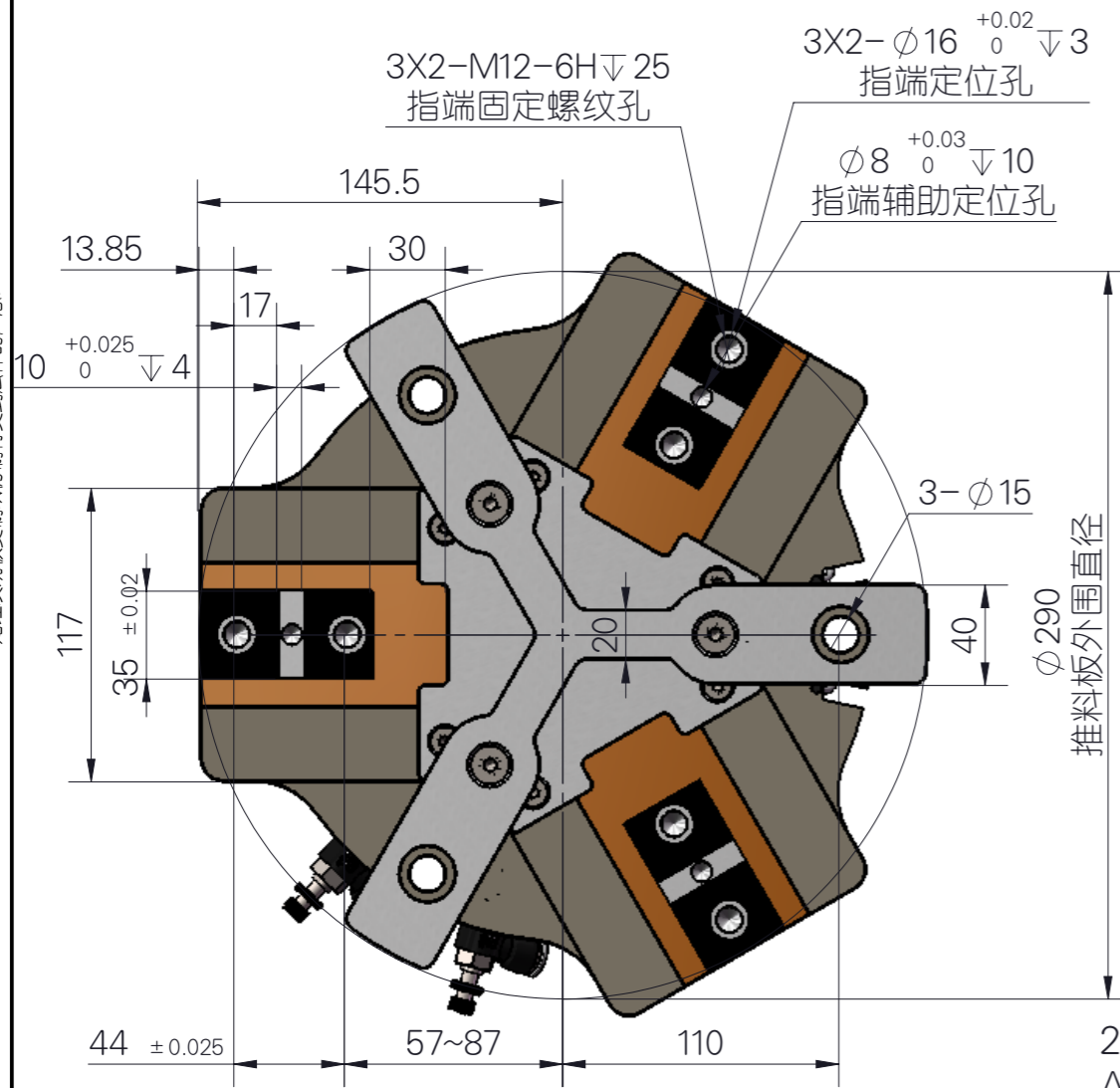




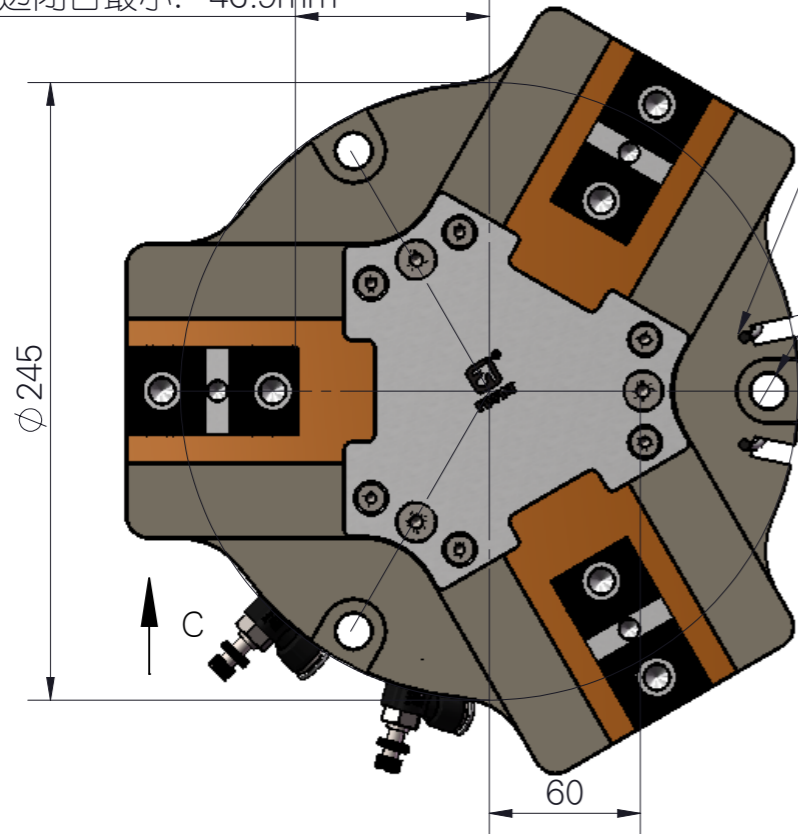
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因改良等原因, 规格以及外观有所变更时, 不再另行通知, 敬请谅解。  
Without further notice if specification and exterior have been changed because of improvement thanks for your understanding

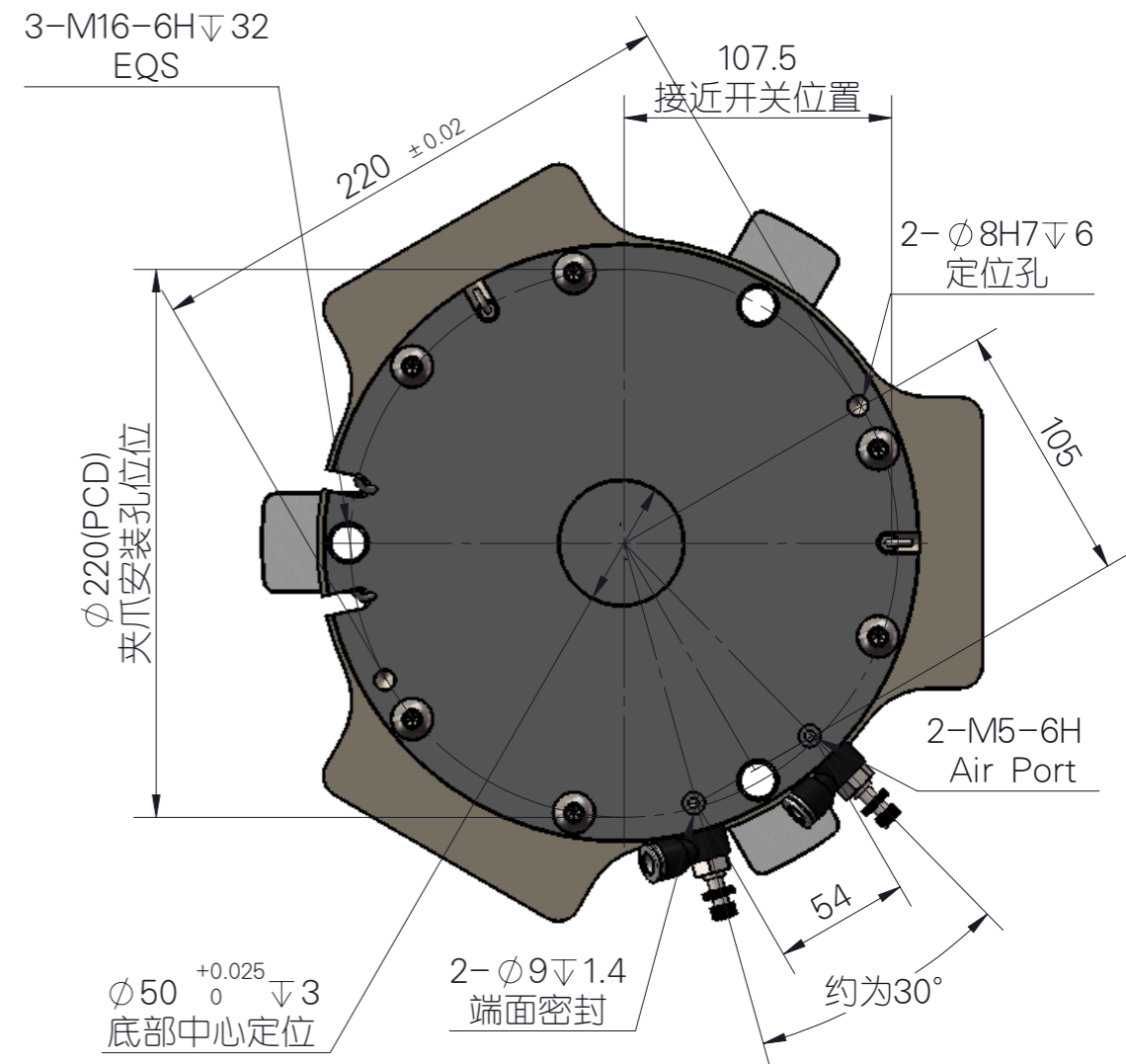
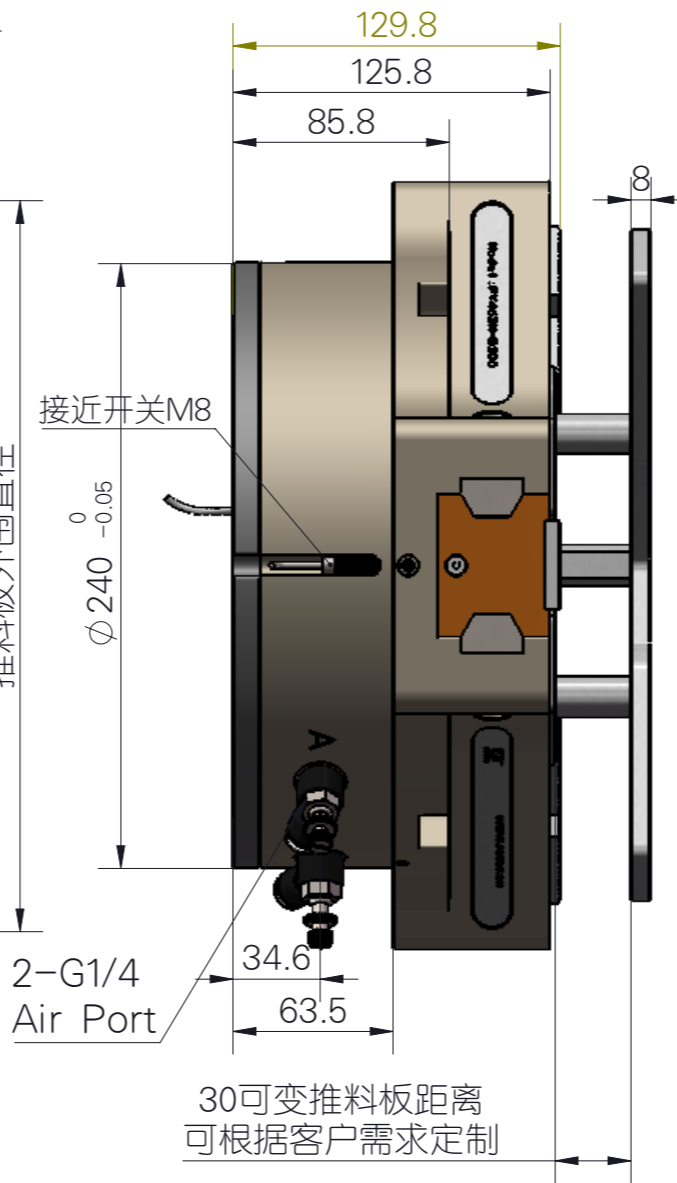
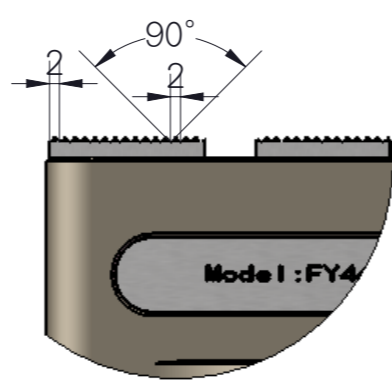


移除推料板视图

单边张开最大: 76.9mm  
单边闭合最小: 46.9mm



C向视图  
带齿滑块 (可选)



名称: 气动平行三爪  
Name: Pneumatic parallel three claws  
型号 (Model): FY46ZM-D200  
P: 空气压力 (bar) P: Air Pressure (bar)  
L: 到作用点距离 (mm) L: Exertion Length (mm)  
开闭范围 (Stoke): .60mm  
产品重量 (Weight): 20.05kg  
最大附件长度 (Max. length attach): 355mm  
配管接口 (Fitting size): PF (G)1/4  
理论夹持力-开 (Gripping force : Open): 12540N  
理论夹持力-闭 (Gripping force : Close): 12130N  
  
开闭时间 (Closing/Opening time): 0.12/0.25sec  
重复精度 Repeat accuracy: 0.05mm  
连续使用次数 (Continuation usage amount): 20  
使用气压 (Operating pressure): 3-8bar  
周围温度 (Ambient temperature): -5 to 60°C (-10 to 130°C)  
润滑 (Lubrication): 不需要 (Needless)  
根据 IEC60529 标准安全防护: IP64  
Safety protection according to IEC60529 standard: IP64  
所有数据在 6 Bar 时测量 (All data were measured at 6 Bar)  
重复精度: 连续动作 100 次以后的检测值  
After 100 consecutive strokes to end positions

警告:  
1. 当操作夹爪工作时, 请人员务必远离夹爪和机器人的活动部位, 否则将会造成人身伤害的危险;  
2. 由于不同物件有其不同的摩擦系数, 当初次夹持工件时, 请在空旷场地进行试夹, 确保夹稳后方可装机工作, 否则将会有跌落工件砸伤机器或人员的风险  
Warning:  
1. When operating the gripper, please keep away from it Gripper and robot's moving parts, otherwise it will Risk of personal injury;  
2. Because different objects have different friction coefficients, When clamping the workpiece for the first time, please try clamping in an open field. Ensure that the clamping is firm before the machine can work, otherwise it will There is a risk that falling workpieces may damage machines or personnel.