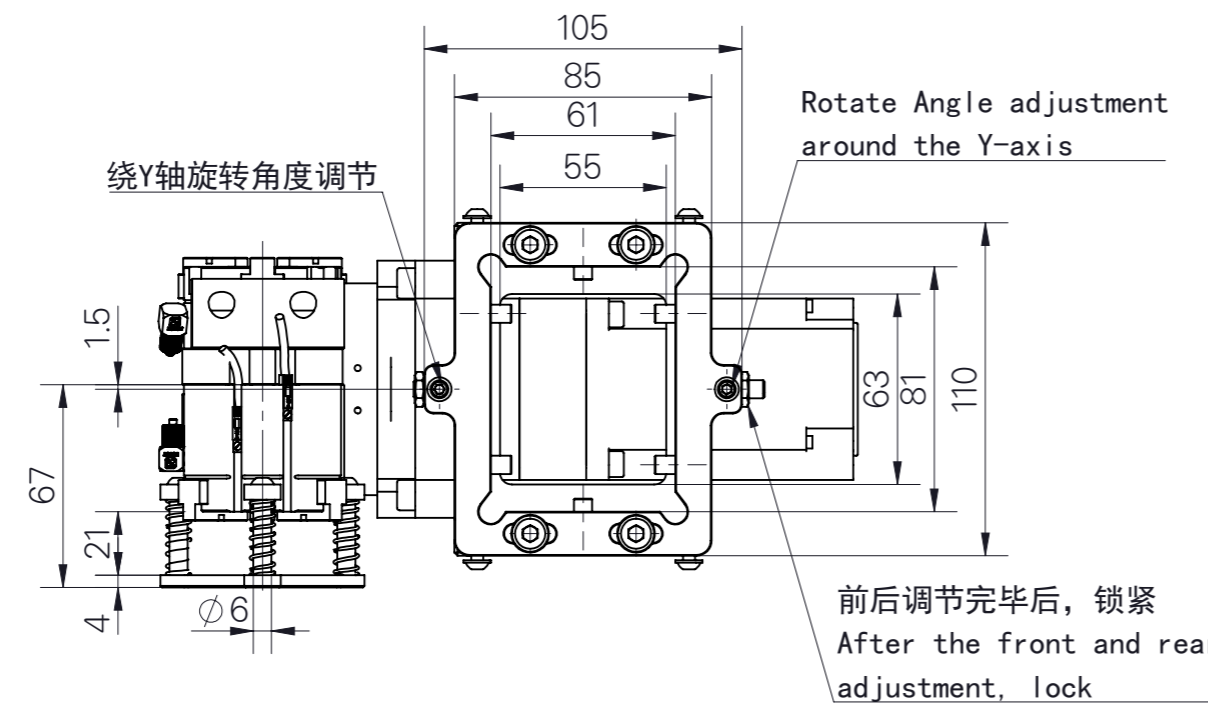
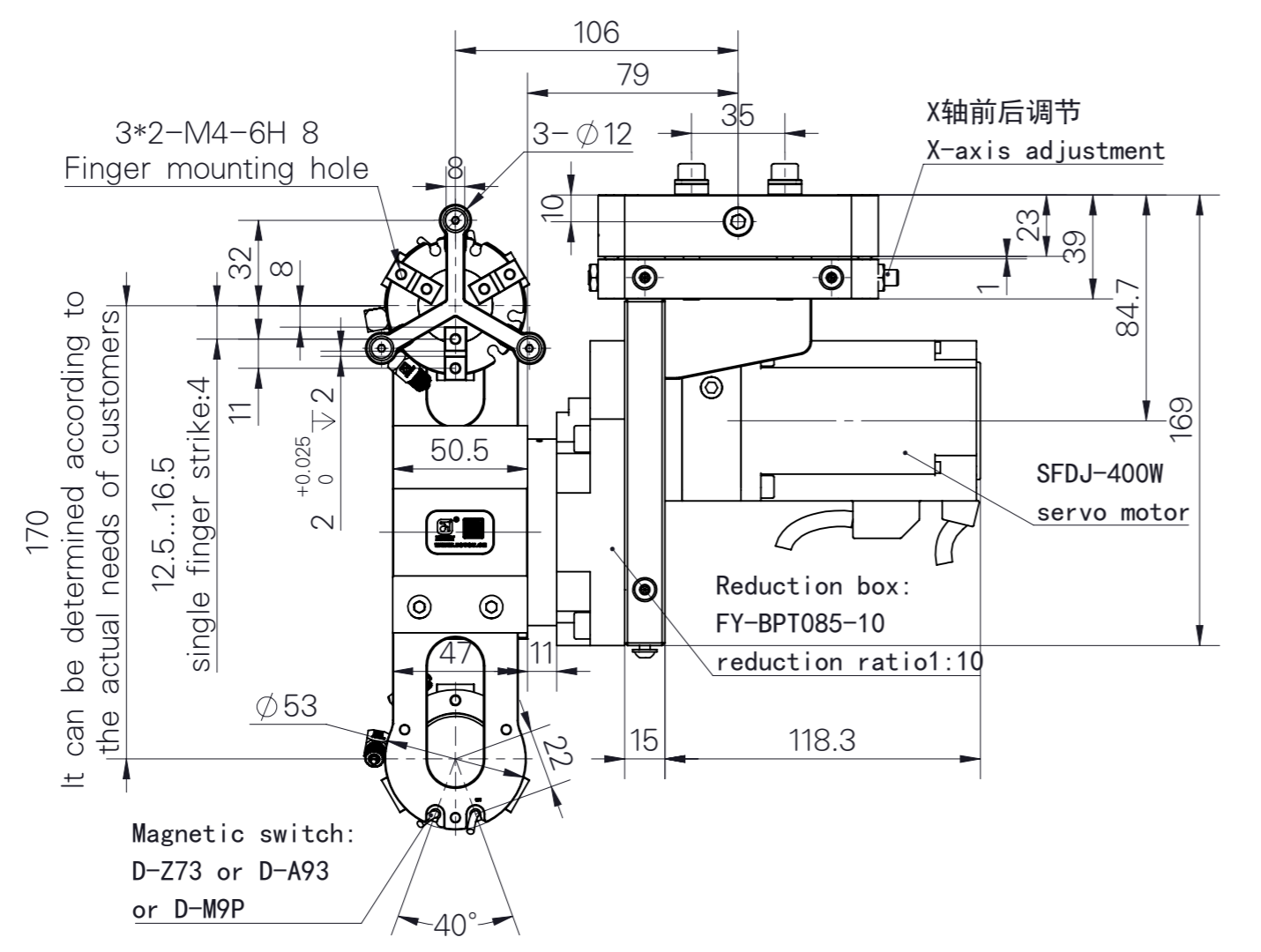


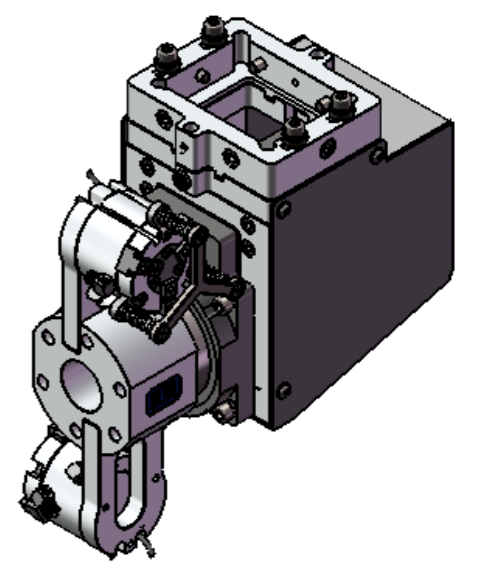
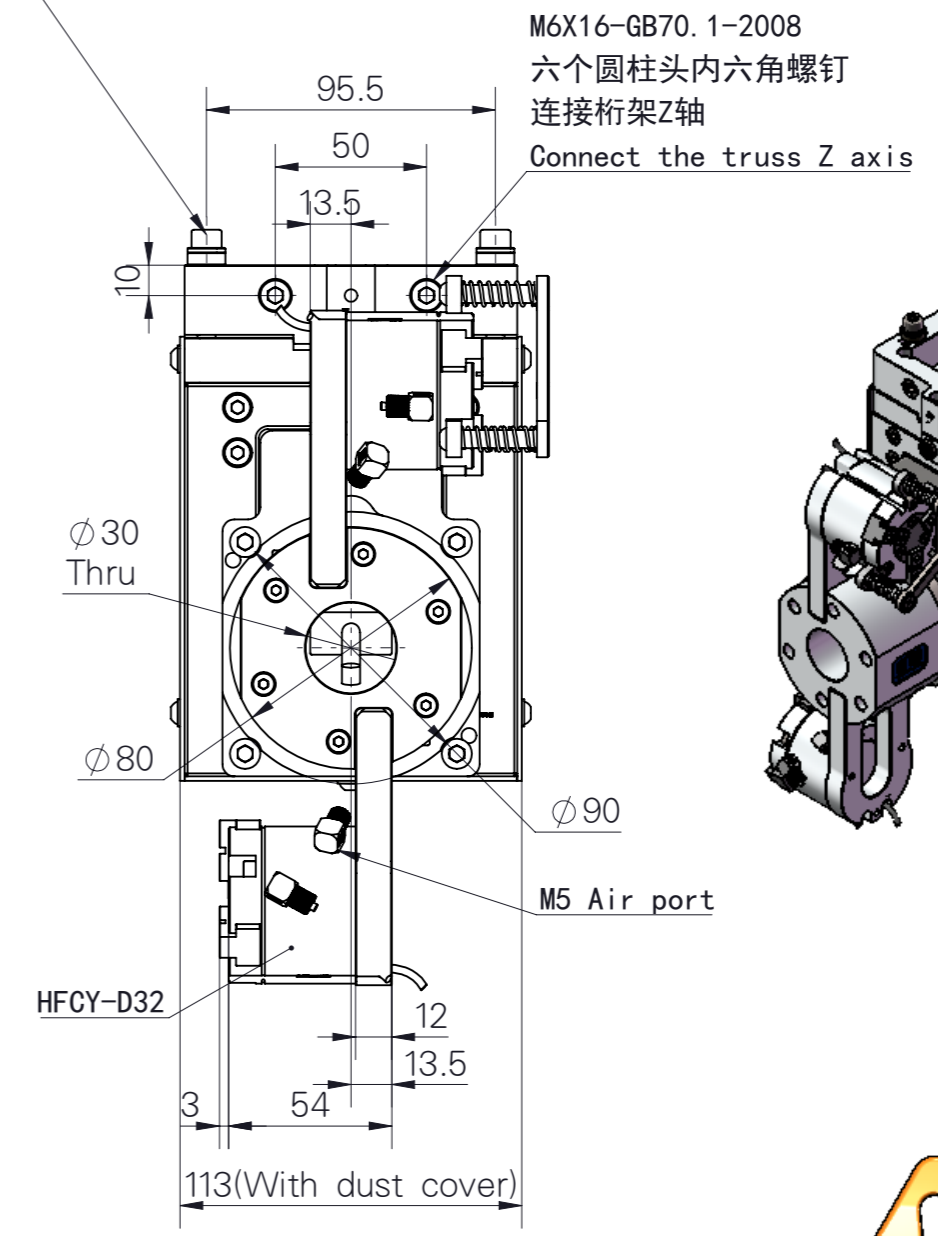


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 Without further notice if specification and exterior have been
 changed because of improvement thanks for your understanding



角度和前后调节完毕后再拧紧螺栓固定
Tighten the bolts after adjusting the
Angle and front and rear



名称: 桁架三爪机械手 (Truss three-jaw manipulator)
 型号 (Model): FY-BPT085-10&HFCY-D32-RT180
 开闭范围 (Stroke): 4X2=8mm
 最大手指长度 (Max. length jaw): 45mm
 配管连接口 (Fitting size): M5-6H
 带防护罩重量: (No shields weight): 7.2kg
 单指理论夹持力-开 (Gripping force :Open): 74N
 单指理论夹持力-闭 (Gripping force : Close): 82N
 开闭时间 (Closeing/Opening time): 0.025/0.025sec
 重复精度 (Repeat accuracy): 0.02mm
 使用气压 (Operating pressure): 3-8bar
 周围温度 (Ambient temperature): -5 to 60°C (-10 to 130°C)
 润滑 (Lubrication): 不需要 (Needless)
 根据IEC60529标准安全防护: IP54
 Safety protection according to IEC60529 standard: IP54
 所有数据在 5 Bar时测量 (All data were measured at 5 Bar)
 重复精度: 连续动作100次以后的检测值
 After 100 consecutive strokes to end positions

警告:
 1.当操作夹爪工作时, 请人员务必远离夹爪和机器人的活动部位, 否则将会造成人身伤害的危险;
 2.由于不同物件有其不同的摩擦系数, 当初次夹持工件时, 请在空旷场地进行试夹, 确保夹稳固后方可装机工作, 否则将会有跌落工件砸伤机器或人员的风险
 Warning:
 1.When operating the gripper, please keep away from it Gripper and robot's moving parts, otherwise it will Risk of personal injury;
 2. Because different objects have different friction coefficients, When clamping the workpiece for the first time, please try clamping in an open field. Ensure that the clamping is firm before the machine can work, otherwise it will There is a risk that falling workpieces may damage machines or personnel.